Operation Instructions

M-506 Microwave Motion & Infrared Safety Sensor

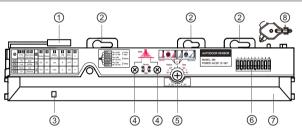


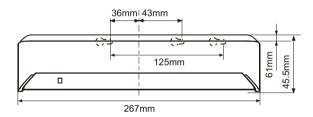
Safety Instructions



The device must be protected with safety insulation at low voltage. All adjustment and maintenance work must be carried out by a professional engineering installer.

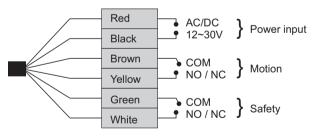
2 Product Overview





① Connector
② Installation hole
③ Action indicator light
④ Safety width adjustment screw
⑤ Depth angle adjustment screw
⑥ DIP switch
⑦ Detecting window
⑧ Adjustment tool

3 Wiring Diagram



Note: 1, When connecting the wire, please don't tear the protection cover, as this may cause a electric leakage hazard or sensor failure.

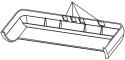
2,Check whether the sensor is properly connected to the door controller. power the sensor and adjust its detection range.3,Please don't enter the detection area after power on and during the green LED light flashes.

4 Installation

- 1, Measure and mark the positions of the installing holes, according to the installation diagram.
- 2, Drill two fixing screw holes of ø3.5mm.
- 3, And drill one wiring hole of ø8mm.
- 4, Fix the sensor tightly by 2 screws.

NOTE: Please install the sensor on the door head as low as possible, but make sure the sensor is not lower than the bottom of the door head.

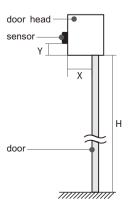
If wiring with surface-mounted way, can cut the outside shell concealed hole wire.



If wiring with surface-mounted way, please cut the concealed holes of outter shell for wiring.

- H. Distance from the ground to the bottom of the door head.
- X. Distance from the door to the fix surface.
- Y. The maximum distance from the bottom of door head to the sensor.

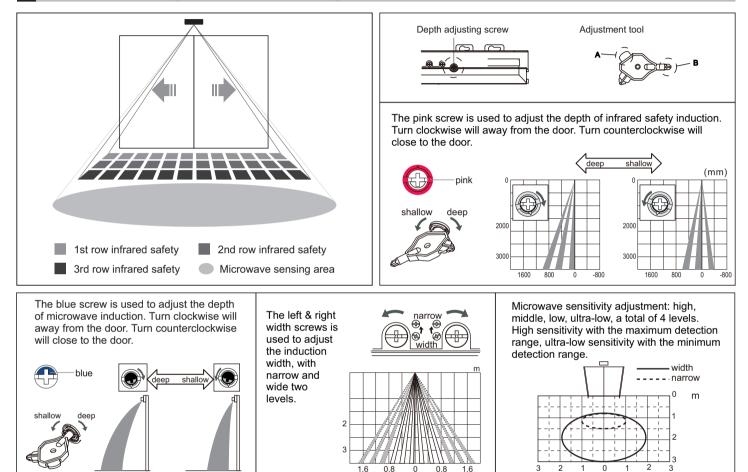
| | | | | | (mm) |
|-----|------|------|------|------|------|
| X | 2000 | 2200 | 2500 | 3000 | 3500 |
| 50 | 200 | 200 | 200 | 200 | 200 |
| 100 | 180 | 180 | 180 | 180 | 200 |
| 150 | 100 | 100 | 120 | 150 | 170 |
| 200 | 50 | 80 | 100 | 120 | 140 |



5 DIP Switch

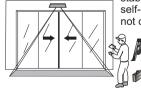
| 1 2 Time selector | 3 Motion | 4 Safety | 5 Safety Sensitivity | 6 A/B channel | 7 Bluezone | 8 | 9 10 Microwave sensitivity |
|---------------------------|-------------|--------------------|-------------------------|------------------|----------------------|---|-------------------------------|
| ↓↓ 15s ↑↓ 1min | T NC | ↑ NC | 1 Low | ↑ В | 1 OFF | - | ↓↓ High ↑↓ Middle |
| ↓↑ 30min ↑↑ Not update | ↓ NO | ↓ NO | ↓ High | ↓ A | ↓ ON | - | Low Low Ultra-low |

6 Microwave sensitivity & infrared detection range



Attentions

When the sensor is powered, the green light flashes and output the door opening signal. In the safety detection range, the sensor detects the

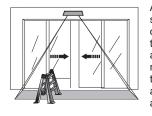


stable background for 8 consecutive seconds, self-learning is successful. Green light is on and not output the door opening signal, sensor will enter the standby state. (NOTE: During the self-learning process,

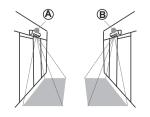
all irrelevant background objects must be removed from the detection range, such as workers, ladders, toolboxes, etc.)



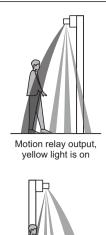
When put one static object in the safety presence detection range, the sensor will trigger the door opening signal in time. (As the picture shows)



After continuously hold for 15 seconds(15s,1min,30min are optional), no other objects or human bodies appear in the detection range, the system will automatically learn the static object as the new background. And it will no longer trigger the door opening signal, and automatic door will close back automatically(As the picture shows).



When installing two sensors in adjacent areas, please separately choose channel A and channel B to avoid mutual interference and misoperation.



Bluezone ON: No induction Bluezone OFF: Safety relay output,



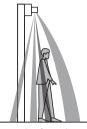
Motion and safety relay output, red light is on



Bluezone ON: No induction Bluezone OFF: Safety relay output, red light flashes



Safety relay output, red light flashes



Motion and safety relay output, red light is on



Safety relay output, red light flashes



yellow light is on

9 Parameters

red light flashes

| Power input: | AC/DC 12~30V(±10%) | | | | |
|-----------------------------|---|--|--|--|--|
| Wire length: | 2.5m | | | | |
| Signal output: | Relay, 1 way motion, 1 way safety (NO/NC optional) | | | | |
| Installation height: | 3500mm(max) | | | | |
| Static current: | 75mA (DC 12V power) | | | | |
| Action current: | 150mA (DC 12V power) | | | | |
| Dimension: | 268(L)x61(W))x38(H)mm (exclude the bottom shell) | | | | |
| Material: | Optical surface with PMMA, shell with ABS | | | | |
| Working temperature: | -25°C~55°C | | | | |
| Infrared Safety | | | | | |
| Ray type: | Infrared modulated ray | | | | |
| Ray source: | infrared 940nm | | | | |
| Light beam: | 1 way motion and safety, 12 light spot; 2 way safety, 24 light spot | | | | |
| Self-learning time: | ime: Dynamic stable learning for 8 seconds | | | | |
| Led indicator: | Standby mode in Green LED, 3nd row infrared ray's action mode, Red LED is always on; | | | | |
| | 1st and 2nd row infrared ray's action mode, Red LED flashes. | | | | |
| Detection range: | 2500(W)×600(D)mm (Installation height=2.5meter) | | | | |
| Output holding time: | : 1.2s | | | | |
| Response time: | ≤150ms | | | | |
| Background update time: | 15s, 1min, 30min, not update, 4 levels optional | | | | |
| Microwave motion | | | | | |
| Technology: | Microwave and microwave processors | | | | |
| Frequency: | 24.125GHz | | | | |
| Transmitting power: | <20dBm EIRP | | | | |
| Transmitting power density: | <5mW/cm ² | | | | |
| Detection mode: | e: motion | | | | |
| LED indicator: | Microwave motion in Yellow LED | | | | |
| Detection range: | 4m(W)×2m(D) (Installation height=2.5meter) | | | | |
| Retention time: | 2s | | | | |
| Packing list: | Sensor *1, operating instructions *1, screws bag *1, 6-pin line(2.5m) *1, bottom shell *1 | | | | |